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Strong Mid-Depth Currents and a Deep Cyclonic Gyre in the Gulf of Mexico

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Strong Mid-Depth Currents and a
Deep Cyclonic Gyre in the
Gulf of Mexico

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About the Cover

The cover figure shows a vertical N-S section at 90°W through the Gulf of Mexico; the contours are the mean E-W velocity from the Princeton model. The deep mean flow to the west along the northern (U.S.) side is observed. The prominent feature along the southern (Mexican) side shows flow to the east at depths of 1500m and deeper. That eastward-flowing deep current has not yet been observed but is predicted by the studies in this report.
Acknowledgements

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I. EXECUTIVE SUMMARY

The main purpose of this work was to explore the possibility that the deep flow (~2000m) around the edges of the Gulf circulates in a cyclonic, or counter-clockwise direction. The existence of such flow was proposed on theoretical grounds but had not been previously documented. Our results are quite clear that such flow is reliably observed.

Recall that the surface flow in the eastern Gulf is strongly anticyclonic as a result of the Loop Current. The surface flow in the western Gulf is also largely anticyclonic as a result of both wind forcing and the presence of large eddies that separate from the Loop Current. So a cyclonic deep flow might appear at first glance to be counter-intuitive. One tacit oversimplification we have made is that the deep flow in both the eastern and western Gulf can be adequately described as a simple large gyre. We suspect that better measurements in the future will lead to an awareness of a richer mean field with more detail, but at the moment the database is not sufficient to allow better resolution. It should be clear that, being strictly a boundary flow, there is ample space for a much more detailed flow in the interior.

Surprisingly, the warm-core temperature and density patterns associated with these surface flows extend to at least 2000m. There are reasons, however, to suspect that the deep mean flow should actually be cyclonic. Topographic wave rectification and vortex stretching contribute to this cyclonic tendency, as will the supply of cold incoming deep water at the edges of the basin. We find that the deep mean flow is cyclonic both in the eastern and western Gulf, with speeds on the order of 2 cm/s at 2000m. Recent moorings in the northern Gulf find even stronger mean speeds.

This report is based on observational and numerical modeling studies and it deals with three separate but related topics. The observations include four separate groups of current-meter moorings at different locations and in different years. The observations range in duration from nearly one year to three years. There was also a major deep-drifting buoy project in the western Gulf that gave supportive results. While this was hypothesized from a theoretical point of view, the conclusive evidence is completely observational. This cyclonic mean deep flow takes place around the edges
of the basin, rather like the well-known deep western boundary current off the east coast of the U.S. We are not aware of any long-term data set that offers conflicting evidence.

The temperature around the edges of the basin at 2000m is coldest near Yucatan Channel, where Caribbean Sea water is colder by ~0.1°C. The temperature increases steadily with distance from Yucatan in the counterclockwise direction, consistent with a deep mean cyclonic boundary flow. The second purpose of the work was to try to explain the rare but persistent findings of strong bursts of flow at intermediate depths, as reported by drilling platform operators. It is possible to search for such bursts of flow in the results from numerical models. The models used here are two of the best-known models in oceanography: The Princeton Ocean Model, which is an outgrowth of the Mellor-Yamada model, and the Miami Isopycnic Coordinate Model, or MICOM. Some strong bursts of flow are found, as reported herein, but while the results are informative, they are not compelling. One fundamental difficulty is that the reported observations of these strong flows continue to be remarkably elusive, so it is difficult to know exactly what one should be looking for in the models and under what conditions.

The third part of our results deals with comparisons between the observations and the numerical modeling results. At this stage in numerical model development, results tend to capture most of the major time-dependent features of ocean circulation rather well. However the mean flows over many years are perhaps not the most reliable part of the results. The interesting result here is that when two "top of the line" numerical models were run by experienced practitioners, one of the models found a deep mean flow that is consistent with the observations, and the other model did not. And the reasons for the differences are the subject of considerable debate. It obviously will require further study to help unravel this mystery. Figure 1.1, which also appears on the cover of this report, is a N-S section through the Gulf at 90°W. Mexico is on the left, the U.S. on the right. The region of flow of ~4 cm/sec (to the west) along the steep slope off the U.S. coast, at depths of 1500-2500m, was found to be quite consistent with two separate long-term current-meter mooring arrays. The observations of this flow are discussed in Section III and the numerical modeling in Section IV.
Figure 1.1. The mean E-W (U) velocity component along a N-S section at 90°W from the Princeton Ocean Model. The mean speed over 5 years is shown in cm/sec.
II. INTRODUCTION

2.1 Introduction

The Loop Current and the warm-core rings that detach from it dominate the upper-layer flow in the Gulf of Mexico. The well-known primary flow enters the Caribbean Sea from the open Atlantic, flows into the Gulf of Mexico through Yucatan Channel and leaves the Gulf to form the Florida Current and Gulf Stream (see, for example, Schmitz and Richardson, 1991; Niiler and Richardson, 1973). There have been several earlier attempts to summarize the flow in the Gulf using the historical data (see Hoffman and Worley, 1986; Molinari et al., 1978). The upper-layer flow has been observed fairly well in recent years by satellite observations of temperature and sea-surface height. The main flow is restricted to approximately 850m as a result of the limiting depth of the Florida Straits.

The deep flow has been described by Hamilton (1990). A magnificent new set of mooring data in the Yucatan Channel has now been reported (Bunge, et al., 2002; Ochoa, et al., 2002; Sheinbaum, et al. 2002). The mean upper-layer flow is well described by almost any temperature or density surface near or in the main thermocline. Figure 2.1 shows an attempt to determine the (long-term) mean temperature at 400m. The mean depth of the 27.0-sigma-t surface shows a similar structure. The dots that appear to be data points are local means of essentially random concentrations of ~5-10 hydro stations. Using data from many years, these were selected from the full historical NODC data base (Conkright et. al., 2000) in an attempt to suppress the very great time variability of warm-core rings propagating to the west.

Two individual warm-core features are evident in Figure 2.1. Although the Loop Current position is notoriously variable, it is well known that a clear mean emerges in the east. In the central and western Gulf the anticyclonic pattern is maintained both by the mean wind field and by the passage of
Figure 2.1. Time-mean temperature distribution at 400m, based on the full historical database from NODC. The individual dots that appear to be data points are local means computed from ~5-10 hydro stations concentrated near the point. The 1000m isobath is shown. The flow between Cuba and Florida is not resolved in these data.
large warm-core rings that have separated from the Loop Current. The relative importance of these two forcing mechanisms remains an open question. The western gyre appears to have southerly flow from ~90°W to ~95°W; the models used here show this flow (see for example the vertical section of velocity at 25°N later in this report). At the far western edge, however, the strong core of northerly flow found in the models is not apparent in the data as a result of poor data resolution. One problem has been that the majority of the older hydro sections run N-S.

Though we know the upper-layer flow fairly well, we do not know the deep flow very well at all. Several numerical models include the Gulf of Mexico, but good observations at depth are scarce. The intriguing fact is that the upper-layer flow, so obviously anticyclonic, appears to extend—in the density field—to depths of ~1500m to 2000m. Because we know that the flow in the Florida Current penetrates only to ~850m we might expect the warm-core structure of Figure 2.1 to extend only to that depth, whereas observations show that it goes much deeper.

Figure 2.2 shows a map of temperature at 1250m. The warm-core patterns are still evident at this depth. They remain evident, if not as clearly so, as deep as 2000m. In the eastern Gulf, the horizontal temperature difference at 1500m is ~0.06 °C between the central region and the eastern edge. In the central Gulf the difference has been eroded to ~0.04°C between the central region and the northern edge. This “temperature difference” signal is still evident at depths of 2000m. Table 2.1 shows the essential information.

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**Table 2.1.** Mean potential temperature, °C, in the centers and edges of the eastern and central Gulf of Mexico. The first value is potential temperature, the second is the number of samples.

<table>
<thead>
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<th></th>
<th>Central Warm Region</th>
<th>Outer Cool Region</th>
<th>Difference Δ T, °C</th>
</tr>
</thead>
<tbody>
<tr>
<td>E. Gulf, 1500m</td>
<td>4.185, 44</td>
<td>4.130, 123</td>
<td>.045</td>
</tr>
<tr>
<td>Central, 1500m</td>
<td>4.142, 32</td>
<td>4.105, 45</td>
<td>.037</td>
</tr>
<tr>
<td>E. Gulf, 2000m</td>
<td>4.050, 19</td>
<td>4.016, 34</td>
<td>.034</td>
</tr>
<tr>
<td>Central, 2000m</td>
<td>4.053, 21</td>
<td>4.024, 19</td>
<td>.029</td>
</tr>
</tbody>
</table>
Figure 2.2. The time-mean distribution of potential temperature at 1250m. The original data set is the same as for Figure 2.1. The isobath shown is 1250m.
A “warm-core ring” in the upper ocean suggests anticyclonic flow, but (as is well known) in deep water this signal tells us only about vertical shear. For reasons put forth in the next section, it seems reasonable to expect that the deep mean flow should be cyclonic. And so we ask, is there evidence for a reversal of the mean flow between ~800m and 1500m?

Some readers may raise the additional question: Why do we care about the direction of deep mean flow? (We might reply rhetorically; why do we care about the direction of the Deep Western Boundary current off the U.S. east coast?) The Caribbean Sea is the only source of deep water for the Gulf of Mexico, for no deep water is formed locally. The Caribbean source of cold deep water (e.g., Bunge, et al., 2002) supplies oxygen and nutrients. The return flow flushes the deep Gulf. Surely the eddy fluctuations are important, but how can we possibly understand the magnitude and effects of these transports if we do not even know the direction of the deep mean flow?

2.2. Why we expect the deep flow to be cyclonic

There are three mechanisms here that could generate cyclonic deep flow. First, it is well known that there is a substantial amount of eddy-like activity over the entire basin at depth, composed mostly of topographic Rossby waves (Hamilton, 1990; Oey and Lee, 2002). Topographic rectification of these waves would contribute to cyclonic mean flow. Second, there is the introduction of cold deep water from the Caribbean, through the Yucatan Channel. At 2000m, the Caribbean is ~0.1°C cooler than the Gulf. Recent observations (e.g., Bunge et al., 2002) show that for intervals of many months the deep exchange can be as large as 5–10 Sv while the Loop Current goes through a ring-shedding cycle. Parcels of water would, of course, gradually lose their temperature deficit as they mix downstream from Yucatan. But we know from observations elsewhere (Mediterranean outflow, Denmark Straits overflow, Caribbean Sea inflow) that cold, dense incoming parcels hug the right-hand slope even after some mixing and sinking. This supply of cold dense water is analogous to, even if weaker than, the supply of North Atlantic Deep Water to the Deep Western Boundary current along the East coast of the United States. This effect also introduces colder water around the periphery, enhancing the existing “warm-core” shear structure.
A third mechanism, we suspect, operates only in the eastern Gulf. During one phase of the Loop Current cycle, as deep Caribbean waters flow over the sill into the Gulf, the “bottom falls away” in the downstream direction. Denser water that enters near 2000m flows into a weakly-stratified region where the bottom drops abruptly to ~3500m. The resultant vortex stretching should induce a cyclonic spin of the entering fluid, consistent with similar findings of Spall and Price (1998). By contrast, when water *leaves* the Gulf during the reverse phase of the Loop Current cycle, the ambient stratification in the Gulf, even though it is weak, tends to restrict the source of outgoing fluid to depths above the sill. So we expect much less vortex compression on the other half of the deep flow cycle.
III. ANALYSES OF AVAILABLE OBSERVATIONS

3.1 Deep temperature structure and vertical shear

3.1.1. Eastern Gulf

We have computed the vertical shear associated with these anticyclonic patterns. Figure 3.1 shows several regions in which we computed the mean hydrographic conditions based on the available NODC database.

Because the variability is so great, we wished to use observations over as great a time span as possible and over as great a horizontal extent as seemed appropriate. From a construction of composite temperature-salinity curves we concluded that observations of temperature have much less apparent error, or scatter, than salinities. For this reason and because the salinity gradients are so small in the deep Gulf, we have chosen to compute density from a mean temperature-salinity curve, using the temperature data alone for gradient information.

In the eastern Gulf, it turns out that the shear profile on the eastern side has a much better signal-to-noise ratio than that on the western side. The western side has sparse observations, contributing to the poor signal-to-noise ratio. The position of the Loop Current is constrained by the Florida shelf on the Eastern side, but not on the Western side, which may also contribute to the greater variability on the Western side.

Figure 3.2 shows the resulting mean temperature signal. Below 1500m, the standard deviation of the temperature variability is ~0.02°C in the central and eastern boxes; Figure 3.2 shows that the temperature differences are on the same order. (The standard error of the means, of course, is smaller.) We computed error estimates in the following way. Because the standard deviations of the temperature data values are as large as the signal, we estimated a standard error of the mean by computing the composite mean values between 1000 and 2000m. The temperature difference on the eastern side was 0.13°C, with a standard error of the mean of 0.03°C, based on 106 observations in the east, 163 in the center. We are not able to compute the details of the vertical shear with great accuracy, although the mean difference is reliably greater than the standard error. It should be
Figure 3.1. Location of the regions used to form data means for constructing shear profiles.
Figure 3.2. Mean vertical temperature distributions in the eastern Gulf of Mexico; an expanded scale is shown in the lower box. The regions used are shown in Figure 3.1.
emphasized, however, that the biggest variability in these data is not in the usual sense of “error,” but in time. Multiple data points on a single hydrocast are not independent in the way we would like. The vertical averaging, however, will reduce problems from instrumental errors, internal waves, and other such sources. Therefore, the significance level is not nearly as high as one would like. Nevertheless, the same result holds true for all the individual calculations: the signals are small but consistently of the sign appropriate to support the idea of cyclonic flow. The geostrophic velocity computed from this temperature-density distribution is in Figure 3.3. The flow at 2000m relative to 1000m is ~1 cm s\(^{-1}\) to the north. It is weak but reliably above the noise level. It remains, of course, to determine an appropriate but believable reference level for the geostrophic calculation. To anticipate the results of the next sections, however, we point out here that a 1000m reference level turns out to be a remarkably good choice.

The signal-to-noise ratio in our calculation is barely adequate on the east side of the Gulf, but is even worse on the western side. The mean temperature difference, only 0.05°C, has a standard error of 0.04°C. There are a number of reasons why the computed signal could be so small. We are unable to offer any definitive explanation; beyond noting the fact that the data are quite sparse on the western side, further speculation seems pointless. The distribution of the number of stations in the eastern region (the region with more data) is shown in Figure 3.4.

### 3.1.2 Central Gulf

In a fashion similar to our methods in the eastern Gulf, we have computed the mean geostrophic vertical shear in the central area of the Gulf using the regions shown in Figure 3.1. Figure 3.5 shows the velocity structure relative to 1000m. The velocity profile is shown for only the northern side of the Gulf because the signal-to-noise ratio is below the noise level on the southern side.

The flow at 2000m, relative to 1000m, is to the west in Figure 3.5, again suggesting a cyclonic flow pattern. (As before, the issue of justifying the choice of reference level is postponed to the next section.) The velocity at depth is only a few tenths of a cm s\(^{-1}\). This value seems almost ridiculously small, but we note that, first, it is to the west, consistent with theoretical expectations. Second, the shear profile at depth is monotonic almost to the bottom. (We would not bet heavily on the small bend at the bottom.)
Figure 3.3. The mean N-S geostrophic speeds relative to 1000 db computed from the temperature profiles of Figure 3.2 and using a mean T-S curve.
Figure 3.4. A histogram of the number of hydrographic observations at each depth for the eastern region (shown in Figure 3.1) of the eastern Gulf for these calculations.
Figure 3.5. The mean E-W speeds, relative to 1000 db, computed from the temperature signal in the central Gulf. The result is shown for the deeper section only for the northern half, where the signal-to-noise ratio allows a significant result.
actual velocity signal of the expected flow, if it is concentrated in a fairly narrow region near the boundary, will of course not be sampled closely in these average data. Thus high speeds would be almost impossible to see by this calculation, although we should certainly get the sign right. These factors all support the cyclonic hypothesis we have put forward.

3.1.3 Western Gulf

The averaging areas, or boxes, shown in Figure 3.1 also show areas in the western Gulf where we made calculations similar to those shown previously. Figure 3.6 shows the velocity profile in the southwestern Gulf; there we see speeds (relative to 1000m) of order 0.5 cm s\(^{-1}\). The flow is to the south. This result, too, based on data completely independent from that of the previous sections, is consistent with the assumption of cyclonic flow. For the northern region in the western Gulf, however, the signal does not emerge above the noise.

3.1.4 Variability of the geostrophic shear

The geostrophic results presented in the preceding sections show our best attempts at determining mean values. To what extent, one wonders, is it possible to estimate the variability of the geostrophic velocity?

Figure 3.7 shows a collection of 46 station pairs from which we can compute individual velocity shear patterns. The stations in each pair are from a single cruise. The data are from the same dataset as those in the previous section, but are treated quite differently. The reason for this additional calculation, obviously, is that we assumed (or at least hoped) that using pairs of stations from individual cruises might improve the accuracy of the individual calculations because calibration issues would be minimized.

As would be expected, the means from these calculations are essentially the same as from the previous calculations. There are many reversals in sign, but similar means emerge. In an attempt to construct the most accurate values, we have computed an absolute mean at each level from which to compute the standard deviations. Table 3.1 shows these results. In this case only, the values are computed relative to 2000m, to allow consistent comparisons at varying depths. It is obvious that the standard deviations of the values are similar to the speeds themselves (perhaps because the means
Figure 3.6. The mean N-S geostrophic speeds relative to 1000m in the Western Gulf of Mexico.
Figure 3.7. Locations of station pairs (from single cruises) from which geostrophic velocities can be computed. Results are shown in Table 3.1 (see text).
Table 3.1: The mean velocity shear and standard deviation relative to 2000 db. The values were calculated by finding the magnitude of all the individual station pairs and taking the mean and standard deviation.

<table>
<thead>
<tr>
<th>Depth</th>
<th>Mean Velocity Magnitude (cm s⁻¹)</th>
<th>Standard Deviation of Velocity (cm s⁻¹)</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>16.7</td>
<td>15.0</td>
</tr>
<tr>
<td>500</td>
<td>5.7</td>
<td>5.1</td>
</tr>
<tr>
<td>1000</td>
<td>2.1</td>
<td>2.1</td>
</tr>
<tr>
<td>1500</td>
<td>0.5</td>
<td>0.5</td>
</tr>
</tbody>
</table>

are so near zero). Because these are determined from 46 individual calculations, the standard errors of the mean would be reduced by ~6.7 (i.e., \sqrt{45} ), suggesting that the mean values are indeed significantly different from zero.

There is an important point that perhaps should be emphasized. The mean speeds are small, but the individual velocity values are strong. The fact that the individual velocity values are so large (i.e., the variance is large), we suspect, is why the signal-to-noise-ratio is so small.

3.2. Resolving the reference-level issue: Observations of deep flow

3.2.1 Observations from deep current-meter moorings

Long-term current-meter moorings that are well suited to provide a check on absolute deep velocities are scarce. We have found four sets of current-meter mooring data that are appropriate as a reference for these geostrophic calculations; two older arrays in the eastern Gulf and two recent ones in the northern Gulf. They are summarized in Table 3.2. We deal first with the data farthest south, along the Florida escarpment, taken in an MMS-sponsored program in the early 1980s (Waddell and Hamilton, 1985; Hamilton, 1990).
Table 3.2. Observations of deep currents near the edges of the Gulf of Mexico.

<table>
<thead>
<tr>
<th>Agency</th>
<th>Method</th>
<th>Location</th>
<th>Depths</th>
<th>Dates</th>
</tr>
</thead>
<tbody>
<tr>
<td>NOAA (Molinari)</td>
<td>C-M</td>
<td>W. Fla. Escarp, 27.5°N, 85.5°W</td>
<td>950m</td>
<td>6/78-5/79</td>
</tr>
<tr>
<td>SAIC</td>
<td>C-M</td>
<td>W. Fla. Escarp., 25.6°N, 84.6°W</td>
<td>1100, 1600m</td>
<td>1/83-1/86</td>
</tr>
<tr>
<td>NOPP (Weatherly)</td>
<td>Deep Floats</td>
<td>Western Gulf</td>
<td>~900m</td>
<td>1998-2002</td>
</tr>
<tr>
<td>Ensenada Group</td>
<td>C-M</td>
<td>Yucatan Channel</td>
<td>Full Water Column</td>
<td>9/99-5/01</td>
</tr>
<tr>
<td>GULL (Szabo)</td>
<td>C-M</td>
<td>Northern Gulf, 27N 89W-92W</td>
<td>1500-3300</td>
<td>9/00-11/01</td>
</tr>
<tr>
<td>SAIC</td>
<td>C-M</td>
<td>Northern Gulf, ~90W</td>
<td>32-2164m</td>
<td>8/99-9/01</td>
</tr>
</tbody>
</table>

Figure 3.8 shows the locations; plots of the north-south (along-isobath) velocity from Mooring A are in Figure 3.9. Figure 3.10 shows the mean speeds as a function of depth.

The variability is similar at the other mooring, and the mean speeds at depth are also to the north, but the values are only barely greater than zero. That mooring, however, is farther away from the steeply-sloping face of the West Florida Escarpment.

The spectrum of the N-S velocity component at the deepest instrument shows that the energy peaks at periods of 20-30 days. (This frequency band is typical of topographic Rossby waves and will be found at other moorings as discussed later.) There are ~500 days of total record at the lower instrument, capturing ~20 “periods.” Because the correlation coefficient falls to zero at one fourth of a period for a narrow-band signal, we estimate that there are approximately 80 independent observations. This conclusion leads to an estimated uncertainty (standard error of the mean) of ~0.5 cm s\(^{-1}\). Thus we conclude that the mean value at 1600m (Figure 3.10) of ~4 cm s\(^{-1}\).
Figure 3.8. The locations of current meter moorings A and G.
Figure 3.9. Velocity records at the deepest instruments on Mooring A.
Figure 3.10. The mean velocity profile for speeds at Mooring A.
(to the north) is significantly different from zero by 8 times (!) the standard error of the mean. (Many probability tables do not show results for results greater than 4 times the standard deviation; one's assumptions about the shape of the distribution become crucial.)

Perhaps we should emphasize the main point here: the observed mean speed over nearly 3 years is several cm s$^{-1}$ to the north and significantly different from zero during this time interval. However, considering the large variability of such signals on decadal time scales, we would not assume that this mean value or error estimate is valid for all time. It seems plausible, however, that our choice of 1000 m as a reference level is an effective choice for the purpose at hand. Our estimated mean speed, relative to 1000m, was found to be $\sim 1.1$ cm/sec (Fig. 3.3). To this we may add $\sim 3$ cm s$^{-1}$ (Figure 3.10), suggesting a deep cyclonic speed in the eastern Gulf of order 3-4 cm s$^{-1}$. Since there probably is not a single level of “no motion” in the Gulf, 1000m is used, merely to be able to make comparisons between the geostrophic shear profiles; the current meter moorings suggest that this choice is eminently reasonable.

We also explored the possible coherence between temperature and velocity at these two moorings. If cold bursts of incoming deep water from the Caribbean Sea retain their temperature deficit this far into the Gulf, it would be an interesting finding. Unfortunately, the temperature signals were barely resolved at each instrument, and there was no clear coherence between velocity and temperature. At depths near 1600m, the deepest instrument at Mooring A, the temperature difference between the Caribbean and Gulf water is very small, so lack of coherence there is not surprising. Near sill depth (2000m), the Caribbean is roughly 0.1°C cooler. However, at mooring G the nearest instrument was at ~2360m; temperature record was composed largely of “background temperature,” with occasional departures of a few hundredths of a degree. It seems likely that the instrument was deeper than the incoming bursts of cooler water. Because there were so many “background temperature” data points, which appear as “zero” in a calculation of the spectrum, we considered the calculations of cross-spectral coherence to be of questionable validity.

It is instructive to estimate the transports associated with these deep flows. At Mooring A, the inshore mooring, the mean nearly-barotropic N-S velocity is $\sim 3$ cm s$^{-1}$, over a depth span of at least 1000m and possibly twice
that. If we take the horizontal extent to be only 75 km (the distance to Mooring G, farther offshore) the mean transport is thus estimated to be ~3 to 6 Sv. This mean value applies to a narrow boundary current.

For the stronger bursts of flow, however, the speeds are easily 25-30 cm/sec at Mooring G, and clearly are barotropic to ~3200m. It is hard to escape the conclusion that the transports in these bursts (to the north) are much larger than our estimate for the boundary flow. The estimated transports for brief periods in the deeper layers in Yucatan (see, for example, Bunge et al. 2002) from the recent moorings there are consistent with these surprisingly large values.

Additional evidence for northerly flow along the steep slopes off west Florida, from deep long-term moorings, is found in the work of Molinari and Mayer (1980). They measured the flow at ~1000m offshore of Tampa, FL (near 27.5°N; see Fig. 3.8 above). They show (their Figure 33) that at the uppermost mooring (at 150 meters) there was almost no net along-isobath flow for the whole year (June 1978 to May 1979). At the deepest mooring (950m, 100m above the bottom) there was flow (approximately) to the north, along the isobaths, of the order of 5 cm s⁻¹ in 9 out of 11 months. In the other two months (November and December) the flow was essentially in the noise level. The mean flow at the deepest mooring over the full record was ~3.3 cm s⁻¹ to the northwest, the orientation of the local isobaths. Thus their measurements, although taken in different years, are remarkably consistent with the results of the SAIC moorings shown in Fig. 3.10.

Several current-meter mooring arrays have been installed in the north-central Gulf in recent years. One set of moorings that is relevant to our present discussion was installed by Fugro GEOS in their GULL program. Their array was composed of nineteen moorings on which instruments were placed approximately 100 and 300 m from the bottom, in water depths of ~1600m to ~3400m. Several groups of moorings were located between 89°W and 91°W, from late August 2000 through November 2001. The major difference between the results from these moorings and the data from the West Florida Escarpment is that the flow near steep bottom topography in the northern Gulf near 90°W (i.e., the Sigsbee Escarpment) is somewhat more energetic; the speeds are greater than those shown in Figure 3.9. With these moorings it is possible to see that, in the mean, the deeper flow is strong and toward the west, again consistent with the cyclonic deep flow hypothesis. This dataset remains proprietary at the time of this writing.
The final set of moorings that is relevant to our discussion has been reported recently by Hamilton et al. (2003). There were 5 moorings in an array near 27°N, 90°W, measuring flow especially near the bottom (as well as full water column) at depths near 2000m.

The mean speeds near the bottom, at 2000m, ranged from ~2 to 4.2 cm/sec, all to the west (along the local topography). The highest speeds were seen at mooring I2; this mooring is near the center of the array and near the steepest bottom slopes. At this mooring, which had a 2-year long record, the mean speed at ~11 m above the bottom was 4.2 cm/s, with a standard deviation of 16.75 cm/sec. The TRW energy has a broad peak at ~ 20 days. (Recall that, for relatively narrow-band signals, there are essentially 4 observations per cycle.) For a two-year record the data length suggests a standard error of the mean of ~1.3 cm/s. Thus the mean speed is more than 3 times the standard error, even in a situation with rather large variance. This is indeed significant, as were the results from the other mooring areas. The mean speeds at all 5 moorings were to the west, so if they were grouped, the significance level would be even higher.

### 3.2.2 Observations from deep drifting floats

The best data set we have found that covers a broad region of the Gulf is composed of velocities from an experiment using PALACE (Profiling Autonomous LAgrangian Circulation Experiment) floats. These are a profiling version of the original ALACE floats (Davis, et al., 1991; see also the web site of the manufacturer, [http://www.webbresearch.com](http://www.webbresearch.com)). The National Ocean Partnership Program (NOPP) sponsored this experiment in the Gulf. Approximately four dozen floats were tracked from 1998-2002. A potentially serious problem is that the floats are at the surface for several hours to transmit data. The surface velocities are usually much greater than those at depth. If we were to assume that all the motion takes place at depth, there could be serious contamination of results by surface drift. But navigation fixes at the surface allow the surface drift to be estimated so that the deep float velocities can be corrected for surface motion. We are greatly indebted to our colleagues Georges Weatherly and Nicolas Wienders for allowing us to use their prepublication results (Wienders et al., 2002; Weatherly and Wienders, 2003).
Figure 3.11 shows the computed means and variance ellipses after the corrections have been applied. The mean velocity vectors for this figure were obtained by averaging all the float velocities in 0.5° bins. For these results, only bins with more than 5 float values were used (an admittedly arbitrary choice). While the mean values are small, there is a robust tendency toward a cyclonic pattern. While some regions are sampled poorly (and some not at all), the tendency for cyclonic flow, even at 900m, is evident.

The major purpose here is not so much to determine the velocity at 1000m as to determine the validity of our choice of 1000m as a reference level for the geostrophic calculations. Careful examination of Figure 3.11 shows that the flow at the edges has become cyclonic, albeit weakly, at 900m. Our calculations suggest, of course, that the speeds increase, but only by no more than ~1 to 2 cm/sec, down to ~2000m (see Table 2).

3.3. The path of cold renewal water

At depths of 2000m, the Caribbean Sea is colder by ~ 0.1°C than the Gulf. The results of the Mexican mooring experiment in Yucatan (Bunge et al., 2002) show that cold Caribbean water pours in at Yucatan Channel during every Loop Current cycle. So if there is a deep cyclonic boundary flow, we expect that the temperature around the edges of the deep Gulf should be coldest near Yucatan where the “new” renewal water enters. We would expect that the cold signal, or temperature deficit, would decay with distance “downstream” from Yucatan, as is observed in all such overflow situations (in the Mediterranean outflow, Denmark Strait overflow, etc.; see for example Girton and Sanford 2003).

To examine the possibility of such an effect, Figure 3.12 shows the temperature at 2000m, averaged in one-degree boxes around the edge, plotted as a function of distance from Yucatan. Because the path is irregular, the x-axis is only very roughly a measure of the distance from the source of cold water entering at Yucatan. The individual data are shown, with a smoothed curve through the scattered data points. The increase in temperature with distance from Yucatan is strikingly clear. The sharpest gradient is nearest the entrance at Yucatan, which is consistent with strong initial mixing. Apart from this strong gradient in the first half-dozen data points, a linear fit through the other data would be adequate. The total increase in temperature is ~0.07°C, which is surprisingly consistent with the
Figure 3.11. The mean velocity of drifters at 900m, over the course of several years. The freely-drifting floats surfaced every 7 days; velocity values have been corrected for surface drift effects. These are averaged in ½-degree bins. Courtesy Weatherly and Wienders. Values are shown only for bins that have 5 or more observations.
Figure 3.12. Time-mean temperature around the edge of the Gulf of Mexico at 2000m, averaged in one-degree boxes, plotted as a function of distance from the sill in Yucatan Channel. The x-axis is roughly a measure of distance. The individual one-degree mean data points are shown (x); if a one-degree box had no data, linear interpolation was used for this figure, and the curve connecting the points was smoothed slightly. Except for the data point nearest Yucatan, a least-squares straight-line fit would probably be more than adequate.
net difference in temperature between the two basins. This effect could be interpreted as an indication of the cyclonic boundary flow. However, it is entirely possible that the supply of cold water at Yucatan is one possible mechanism for causing the boundary flow, in a manner similar to that of the Deep Western Boundary Current along the U.S. east coast. The historical data set is adequate at 2000m to see the changes in Figure 3.12, but at greater depths the sampling is concentrated near 2500m and 3000m. The mean (potential) temperature in the Gulf continues to decrease only by ~0.02°C between 2000m and 3000m. A better understanding of the mechanisms and details of the deep-water renewal remain for future work.

For completeness, Figure 3.13 shows the details of the mean temperature distribution averaged in one-degree boxes at 2000m. In each one-degree box, the upper number shows the number of samples from the NODC data base. The mean value has had 4.00 subtracted; the lowest figure is the standard error of the mean in that box.
Figure 3.13 Temperature at 2000m. In each box all available U.S. data were averaged. The number of samples, the mean potential temperature and standard error are shown. From each mean temperature, 4.00°C has been subtracted; thus a value of 7.3 implies a true temperature of 4.073°C.
IV. RESULTS FROM NUMERICAL MODELING:

STUDIES USING THE PRINCETON MODEL

4.1. Description of the Princeton Ocean Model

The numerical model is based on the sigma-coordinate (or terrain-following) Princeton Ocean Model (POM) (Blumberg and Mellor, 1987). For a recent description, please see the web page for this model located at: http://www.aos.princeton.edu/WWWPUBLIC/htdocs.pom. The northwest Atlantic Ocean implementation of the model, known as the Princeton Regional Ocean Forecast System (PROFS), is described in detail by Oey and Lee (2002; http://www.aos.princeton.edu/WWWPUBLIC/PROFS) and by Ezer et al. (2003). The model uses 25 layers in the vertical, with finer resolution near the surface and near the bottom. A curvilinear, orthogonal, horizontal grid is used with resolution that varies from ~5 km in the northern Gulf of Mexico to ~10 km in the Yucatan Channel and ~20 km in the open subtropical Atlantic. The model domain, 55ºW to 98ºW and 5ºN to 50ºN, includes the Gulf Stream, the Gulf of Mexico and the Caribbean Sea. Across the eastern boundary, at 55ºW, constant inflow and outflow transports are specified to account for the large-scale ocean circulation component, while temperature and salinity on the boundary are based on the monthly climatology. The 6 hourly ECMWF winds are used to force the model, as are surface salt and heat fluxes and river runoff. Data assimilation is sometimes included in this model system (Wang et al., 2003), but the analyses done in this project are for runs without data assimilation, so as to account only for model dynamics without data-based corrections.

Oey et al. (2003) conducted studies to evaluate the effect of the open boundary conditions and the “local versus remote forcing” effects on the variability of the Caribbean Sea and the Gulf of Mexico. Experiments with nested grids with doubling the resolution were done as well, but they are reported elsewhere by Oey and his group. Most of the main circulation features of the mean flows remain the same in the case of higher resolution models, though the mesoscale variability is larger and closer to the observed variability. In addition to their material covered in this report, this work has been widely summarized in the published literature. See, for example, Oey and Lee (2002); Oey et al. (2003); Ezer et al. (2002, 2003); and Wang et al. (2003).
4.2. The general circulation in the Gulf of Mexico and comparisons between POM and MICOM

The circulation in the Gulf of Mexico in this model shows a complicated structure with several semi-permanent gyres. Figures 4.1 – 4.5 show the 5-year mean trajectories at 400m, 500m, 1500m, 2000m and 2500 m, respectively. These are trajectories of particles launched at every second model grid point and propagated by the (constant) mean flow for a period of 20 days. The scale vector (in cm/s) represents the distance that a particle with that mean speed would have traveled during this period. These plots can be compared with velocity plots at similar depths from the MICOM model in Section 5 of this report. These semi-permanent gyres are affected by the propagating Loop Current eddies (i.e., averaging the effect of several eddies) and by topographical features. Some gyres are quite similar to those found in the MICOM simulations, but some are different, as would be expected. Both models show the Loop Current quite clearly, of course. The POM and the MICOM indicate an anticyclonic gyre in the western Gulf and a cyclonic gyre in Campeche Bay, in the southwest corner. These are robust features and well known.

At depths below ~1500 m, however, the deep circulation in POM is characterized by a strong boundary-current-like cyclonic circulation, hugging the slopes, consistent with the theory and observational results put forward in Section III of this report, whereas in MICOM a weak anticyclonic circulation is found at this depth along the boundary. In higher resolution POM calculations this boundary current has larger variability and weaker mean, but its main direction remains cyclonic. At 2500 m (2000 m in MICOM) both models indicate a cyclonic gyre around 92-94ºW and 24ºN. Figures 4.3- 4.5 show that the flow near the boundaries is cyclonic—as found in Section III and here—but the interior flow is much more complex than a mere single gyre.

Vertical sections of the flow show us another view of the model results. Figure 4.6 shows a N-S section at 90ºW in the central Gulf. There is a good bit of detail in the interior, but the point of the figure here is to show the strong flows near the boundaries. The flow on the steep slopes along the coast of Mexico is striking. The horizontal maps of Figures 4.1-4.5 show some of the same information of course, but in this presentation it shows up differently. So far as we are aware there are no direct observations of this flow along the Mexican continental rise.
Figure 4.1. Trajectory plot based on the 5-year mean velocity at 400 m depth from POM forced by 6-hourly ECMWF winds but without data assimilation. These are trajectories of particles launched at every second model grid point and propagated by the (constant) mean flow for a period of 20 days. The scale vector (in cm/s) represents the distance that a particle with that mean speed would have traveled during this period.
Figure 4.2 Trajectory plot based on the 5-year mean velocity at 500 m depth from POM forced by 6-hourly ECMWF winds but without data assimilation. These are trajectories of particles launched at every second model grid point and propagated by the (constant) mean flow for a period of 20 days. The scale vector (in cm/s) represents the distance that a particle with that mean speed would have traveled during this period.
Figure 4.3 Trajectory plot based on the 5-year mean velocity at 1500 m depth from POM forced by 6-hourly ECMWF winds but without data assimilation. These are trajectories of particles launched at every second model grid point and propagated by the (constant) mean flow for a period of 20 days. The scale vector (in cm/s) represents the distance that a particle with that mean speed would have traveled during this period.
Figure 4.4. Trajectory plot based on the 5-year mean velocity at 2000 m depth from POM forced by 6-hourly ECMWF winds but without data assimilation. These are trajectories of particles launched at every second model grid point and propagated by the (constant) mean flow for a period of 20 days. The scale vector (in cm/s) represents the distance that a particle with that mean speed would have traveled during this period.
Figure 4.5 Trajectory plot based on the 5-year mean velocity at 2500 m depth from POM forced by 6-hourly ECMWF winds but without data assimilation. These are trajectories of particles launched at every second model grid point and propagated by the (constant) mean flow for a period of 20 days. The scale vector (in cm/s) represents the distance that a particle with that mean speed would have traveled during this period.
Figure 4.6. The mean E-W (U) velocity component along a N-S section at 90W from POM. The upper figure shows the mean speed and the lower figure shows the standard deviation.
Examining this N-S section in some detail, the model allows us to see the different phases of the flow as a large ring passes. Figure 4.7 shows four cross sections of the flow before, during, and after a ring drifts to the west. The schematic in the lower right corner of each figure shows the position of the Loop Current and the ring. The sequence is upper left to lower left, then upper right to lower right. In the third frame, as the ring is centered on the section, a "true believer" might be willing to see hints of a Taylor column of fluid being carried beneath the center of the ring. In such an interpretation the return flow to compensate for mass balance is on either side.

Another difference between the POM and MICOM models is found in the deep circulation in the eastern Gulf, under the Loop Current. Whereas a seemingly barotropic anticyclonic circulation remains in MICOM throughout the water column, a reverse, cyclonic circulation is seen in POM (as well as in Welsh’s calculations using the modular version of the Bryan-Cox-Semptner, or MOM, model).

Comparisons (not shown here) of velocity and temperature cross sections at 26°N and 90°W in the two models support the above results and indicates that the MICOM flow may be more barotropic, while the POM flows are more baroclinic and more strongly affected by bottom topography, creating stronger deep boundary currents. To explain the differences between the results of the two models, one must understand the differences between the two model types. The vertical grid in MICOM follows isopycnal surfaces. Thus in the deep ocean, where stratification is very weak, the resolution can possibly be reduced. The terrain-following vertical grid in POM, on the other hand, as well as the manner in which it has been implemented here, has finer resolution and thus supports intense mixing. This is true both near the bottom, resolving the Bottom Boundary Layer (BBL), and near the surface, resolving the Surface Mixed Layer (SML). Oey and Lee (2002) have shown that the deep boundary current along the slopes of the Gulf is, to a large extent, the result of Topographic Rossby Waves (TRW) induced by fluctuations in the Loop Current and its associated eddies. Adequate resolution near the bottom is necessary to resolve the TRWs. In both models and observations, cross sections of temperature and salinity near the deep boundary current show very weak density gradients, hence the difficulty of calculating these currents from hydrographic measurements as reported in Section III above. These boundary currents are much more pronounced in observations based on floats or current meters, as one would expect. Direct
Figure 4.7. The instantaneous flow pattern along the 90°W section at four phases of a ring passage (from POM). The schematic in the lower right corner shows the positions of the ring and of the Loop Current. The sequence begins in the upper left, then to the lower left; then from the upper right to lower right.
comparisons of POM currents and observations are in fact quite good (e.g., Wang et al., 2003).

4.3. Effects of propagating Loop Current eddies on the deep circulation

The Gulf is dominated by Loop Current eddy shedding events and the westward propagation of those eddies. One of the basic questions yet to be fully investigated is the effect of the eddies on the mean deep circulation. Oey and Lee (2002) have been able to demonstrate the indirect influence of eddies through generation of the TRWs. For example, as eddies propagate to the west they carry fluid with them in the upper ocean, so a return transport to the east is expected. However, the mean horizontal flow is dominated by the much stronger boundary currents and the semi-permanent gyres, so there is no clear evidence as to where this weak return transport occurs; see Figs. 4.1-4.5.

To investigate this interesting question, we show (in Figure 4.8) the net transport below 800 m across 90ºW (blue line). The average surface elevation across the section (green dashed line) indicates that whenever an eddy passes this section (peak in elevation) there is a peak in return transport (below 800 m) with net flow to the east. The correlation between the two curves is striking. By contrast, the net return deep transport, averaged over many eddies, is less than 1 Sv. In comparison with the much larger transports associated with Loop Current Rings, this small transport could easily be lost in the noise and its statistical significance would appear to be questionable. Yet we can be sure that it is a real feature of the circulation, and that the return transport must appear.

One might suspect, a priori, that there should be a Taylor column of fluid being carried along beneath the ring as it travels to the west. The fact that the model indicates increased flow back to the east when a ring passes by seems to suggest that any Taylor column effects, as mentioned in connection with Figure 4.7, are overwhelmed by other parts of the flow field. It may be that the Gulf is simply not big enough in E-W extent to allow the classic effects one might expect.
Figure 4.8. Mean surface elevation across 90°W (green dashed line) as a function of time indicates eddies (positive peaks) crossing the section. The net deep transport below 800 m across 90°W (blue solid line) indicates eastward (positive) deep transport when eddies drift westward overhead.
4.4. Variability of flow in the Yucatan Channel and its relation to variations in the Loop Current

Analysis of the model flow variability in the Yucatan Channel has three purposes. The first is to compare model results with past observations (Maul et al., 1985) as well as more recent ones (Ochoa et al., 2001; Bunge et al., 2002). The second is to understand the forcing mechanisms of the flow; the third, to determine the relation between the Yucatan Channel flow and variations of the Loop Current. For details see Ezer et al., (2002, 2003) and Oey et al., (2003). The structure of the mean flow in the Yucatan Channel as obtained from the POM calculations seems to agree with the main features obtained from the MICOM model. Both models confirm the new finding of the existence of deep return outflows along the slopes of the Channel (Ochoa et al., 2001) and not at the center of the sill as previously thought. The net mean transport in the Yucatan Channel in our model, ~25 Sv, and the large range, ~16-32 Sv (but with no clear seasonal signal), all agree very well with the new observations of the Mexican group. EOF analysis identified the main mechanisms and forcing of the flow variability (see Ezer et al., 2003, and the description of publications supported by MMS below). For example, Figure 4.9 shows that the long-term fluctuations of the inflow from the Caribbean Sea into the Gulf (solid line) is correlated with EOF mode 2 (dashed line) of the inflow velocity across Yucatan Channel. Moreover, almost every event of eddy shedding from the Loop Current (shown by “E”) is associated with a peak in the inflow transport. Such events are also associated with peaks in the return deep transport below 800 m.

Figure 4.10 is something of an unconventional plot and requires a bit of study. It shows the correlation between the changes in the deep flow (positive values in the x-axis represent southward transport below 800 m) and changes in the area of the Loop Current (positive values in the y-axis represent Loop Current growing in area). Data were taken from the passage of three eddies. We see that the deep return transport and the Loop Current extension both grow before an eddy is shed (triangles), and start decreasing afterwards (circles). Using only data points from a two-week interval before and after the ring passes, the correlation increases dramatically to 0.7. This process is consistent with the theory as proposed by Maul. et al, (1985) and recently confirmed from the new Mexican observations (Bunge et al., 2002).
Figure 4.9  Total inflow transport in the upper Yucatan Channel from the Caribbean Sea into the GOM (solid line), the time evolution of EOF mode 2 (dashed line), and eddy shedding events (“E”). (From Ezer et al., 2003).
Figure 4.10. The deep outflow (in the POM) from the Gulf below 800 m (x-axis) and the change in sea level in the Loop Current region; positive y-axis values indicate times when the Loop Current is growing in area. The changes in these parameters for three eddies are indicated: blue triangles are for the two weeks before eddy shedding events; circles are for the two weeks afterward. The linear regression coefficient between deep transport and Loop Current change is 0.4 for all daily values, but is 0.7 if only periods around eddy shedding events are considered. (From Ezer et al., 2002).
V. RESULTS FROM NUMERICAL MODELING: STUDIES USING MICOM

5.1. The Miami Isopycnic-coordinate Ocean Model (MICOM).

Almost all mainstream ocean models in use today are based on the same equations of motion. Different models, however, formulate the solutions in different ways. The Miami model is designed so that the "horizontal" coordinate system follows the slope of the density field of the ocean. This choice does not automatically solve all problems, but its purpose is to:
• avoid inconsistencies between vertical and horizontal transport terms that cause (among other things) false diapycnal mixing;
• hide truncation errors associated with horizontal transport behind the smoke screen of isopycnal mixing.

The model is in widespread use in the ocean modeling community and is well described on their home page:

http://oceanmodeling.rsmas.miami.edu/micom/

5.2 The general circulation patterns in the Gulf of Mexico from MICOM.

The upper-layer circulation in the Gulf is, of course, anticyclonic. The main result from the analysis of the MICOM simulation of the horizontal circulation in the Gulf of Mexico is that the circulation is reversed in the deep waters. Figure 5.1 shows the 6-year averaged Eulerian circulation at 400m; an anticyclonic (clockwise) gyre appears, with two circulation cells in the west. The northern cell is anticyclonic, in part because most of the Loop Current rings end their lifetime in this region. An intense jet is observed on the western side of the anticyclonic gyre. South of this region, the model shows a cyclonic circulation cell. Deeper in the Gulf, the dominant feature remains the western jet of the anticyclonic gyre flowing along the shelf slope of the Gulf of Mexico. Figure 5.2 shows a similar view at 900m.

On the other hand, the cyclonic circulation cell becomes weaker with depth and has shifted slightly to the east of the south corner of the western Gulf. Figure 5.3 shows the mean flow at 1250m, and Figure 5.4 shows the mean flow at 1500m. Finally, Figure 5.5 shows that at 2000m the dominant circulation is cyclonic. The current is to the west in the deepest part of the
Figure 5.1. The mean velocity field from the MICOM model at a depth of 400m.
Figure 5.2 The mean velocity field from the MICOM model at a depth of 900m.
Figure 5.3  The mean velocity field from the MICOM model at a depth of 1250 m.
Figure 5.4. The mean velocity field from the MICOM model at a depth of 1500 m.
Figure 5.5. The mean velocity field from the MICOM model at a depth of 2000 m.
Gulf, veers to the east in the western Gulf and flows along the southern shelf slope. North of the cyclonic gyre, a weak anticyclone is still present. In the Loop Current area, the horizontal circulation in these model results is always anticyclonic. This pattern is not the same as found in the Princeton model nor does it agree with observations. We are continuing to study this feature.

While this project has focused on the mean flow around the edges of the deep Gulf, it remains true that the mean flow is not always the topic of greatest interest to some readers (nor one of the most robust features of model results). To show a measure of the energy of the flow, Figure 5.6 shows the standard deviation of the flow at 900m. Figure 5.7 shows the equivalent standard deviation at 1500m. At 900m the standard deviation ranges from ~2 cm/sec in the west to 6 cm/sec beneath the Loop Current. It is clear that these values are as large as the mean flow itself. The means and standard deviation decrease only slightly at 1500m and the general conclusion remains the same.

5.3. **Strong current events near the bottom of the Gulf of Mexico**

In MICOM simulation, we followed the occurrence of strong current events in the depth range 500-1500m on the northern shelf slope of the Gulf of Mexico over six years. The peak speeds in the model are about 28 cm/s between 500 and 600 m and 20 cm/s between 1300 and 1600m. Those events are strongly associated with the generation of Loop Current rings in the eastern Gulf and with its westward motion. This finding is especially clear when these events occur on the northern shelf of the Gulf of Mexico between 90°W and the western gulf. Figures 5.8 and 5.9 show the current bursts using longitude-versus-time diagrams. These plots show their propagation to the west as well as their intensity.

5.4 **Meridional distribution of the zonal transport at 90°W**

In this section we address the transport budget across a meridional section at 90°W. Somewhat arbitrarily, we divided the section through the middle of the Gulf of Mexico, resulting in a northern and a southern half. The transport budget reveals an anticyclonic pattern with more flow going to the east in the northern half and more going to the west in the southern half. All the increases of current transport in both directions are associated with a Loop current ring passage. During those events, the transport in the deep
Figure 5.6. The standard deviation of the velocity field at 900 m; see for comparison Figure 5.2.
Figure 5.7. The standard deviation of the velocity field at 1500m.
Figure 5.8. The amplitude of current bursts in layer 10, in a latitude-time diagram, upper; the location of the burst (latitude) is in the lower panel.
Figure 5.9. Longitude-time plots of the amplitude and location of strong bursts in layer 13.
layers also increases, as shown in Figure 5.10. The budget result gives a weak eastward transport of 0.08 Sv (1 Sv = 10^6 m^3/s), with a weak eastward component above 1300m (0.26 Sv) and a westward one below (-0.17 Sv). The paths followed by the water parcels are given by the Lagrangian trajectories as described in the next section.

5.5 Lagrangian trajectories in the deep Gulf circulation.

One of the goals of this study was to determine whether some of the Gulf of Mexico waters have a net transport returning to the Caribbean Sea below the depth of the sill in the Florida Strait. The previous results showed a strong eastward transport in the northern half of the Gulf; the Eulerian currents between 1000 and 2000m suggest a return flow from the north to Caribbean Sea (see Figures 5.3, 5.4). Figure 5.11 shows a collection of Lagrangian trajectories in layer 13 of the model. Layer 13 occupies the depth range ~900-1400 m in the Yucatan Channel. We see that the water parcels that return to the Caribbean Sea come from the northern Gulf in a region located east of a ring that has recently separated. These trajectories were obtained as the Loop Current ring was moving to the west and the path of the Loop Current was going straight from the Caribbean Sea out through the Florida Straits. In the model no flow beneath layer 13 was observed to return to the Caribbean Sea just after a Loop Current ring formation.

Finally, we examine the model Lagrangian trajectories in the intermediate layers, between 400 and 1000 m. These trajectories reveal new patterns of the circulation not visible in the above circulation vector plots. Because of the cyclones generated during the formation of a Loop Current ring, some water parcels can be entrained against the main stream. Therefore, instead of following the anticyclonic gyre described above, the water parcels undergo a cyclonic motion initiated east of a Loop Current ring in the eastern Gulf. Figure 5.12 shows particles that drift to the southwest and then return to the east. Those very surprising motions are similar to those that have been observed in actual float trajectories.
Figure 5.10. Time series of transports across a N-S section at 90°W. Top panel shows net transports above and below layer 12 (approximately 1300m). Lower two panels show transports to the east and to the west, in the northern and southern halves of the section.
Figure 5.11. The Lagrangian trajectories of particles in layer 13, originating in the northern and central regions of the Gulf. The particles are launched along the red N-S line at the squares; the end points of the paths are shown by the stars.
Figure 5.12. Lagrangian trajectories in layer 12 for two different time intervals. The particles are launched along the red N-S line at the squares; the end points of the paths are shown by the stars; see text.
VI. Annotated Bibliography

6. A brief discussion of publications resulting from MMS support of this project.


The deep flow variability in the vicinity of the Yucatan Channel between the Caribbean Sea and the Gulf of Mexico is examined within a high resolution numerical simulation of the North Atlantic Ocean. First, since the model is forced with daily ECMWF forcing, the circulation in the vicinity of the Yucatan channel presents a high variability in the flow regimes and in the shedding period which is in good agreement with earlier observations. The outflow (towards the Carribean Sea) in the Yucatan Channel is shown to be in part controlled by the regular east-west shift of the core of the Loop Current in phase with the transport variations. The outflow is shown to compensate the excess of inflow whatever the Loop Current extension. The analysis of the growth of the loop is also shown to be in good agreement with the retroflexion paradox and with the ballooning process proposed by Pichevin and Nof (1997) and Nof and Pichevin (2001) to explain the Loop Current Ring formation. Moreover, at the end of each cycle of Loop Current ring formation a sudden deepening of the loop occurs together with an intensification of the transport and the currents in the deep layers underneath the Loop Current. This process is shown to be connected with the growth of an instability, probably barotropic, as originally proposed by Hurlburt and Thompson (1982).


The formation of the Loop Current rings is studied by comparing the growth of cyclones around the Loop Current ring, during its formation stage, in the very high resolution MICOM simulation with a case study model. In this case study ring; and those cyclones are responsible for the cleavage between the Loop Current ring and the Loop Current itself. Secondly, the Campeche
bank forces the mode 3 instability (3 growing cyclones) of the Loop Current ring. The steady state is a pentapole, which consists in an anticyclone surrounded by four cyclones. Thirdly, the slope of the northern Gulf compensates the beta effect what prevents the instability to grow as a mode 1 which produces only one big cyclone north of the anticyclone.

DeHaan, Christopher J., 2002. Determining the Deep Current Structure in the Gulf of Mexico and the Yucatan Strait from Multiple Data Types. Doctoral Dissertation, Dept. of Oceanography, Florida State University, Tallahassee. October, 2002. This Dissertation is the basis of the journal article described below. Dr. DeHaan is now an oceanographer at the U.S. Navy Oceanographic Office, Stennis MS.


This paper examines the historical density field of the Gulf as well as all the available direct current observations. Using moored current meter data and deep drifting floats, they conclude that the deep (~2000m) flow around the edges of the Gulf is cyclonic. Section III of this report is based heavily on this paper.


Results from the POM numerical simulations of the Gulf of Mexico are shown to compare very well with past and recent observations of velocities and transports in the Yucatan Channel. The main model inflow into the Gulf is found near the surface in the western part of the Channel, while return flows back into the Caribbean Sea are found near the surface on the eastern side of the Channel and along the eastern and western slopes around 1500 m depth. The location and transport of each one of these flows are in good agreement with recent observations (Ochoa et al., 2001). Variations in the upper inflow and deep outflow transports seem to correlate with variations in the extension of the Loop Current, as suggested by analyses of observations (Bunge et al., 2002). Such correlations were found to be especially high near the time when Loop Current eddies are shed into the Gulf of Mexico and return deep transports out of the Gulf are significantly larger.

An Empirical Orthogonal Function (EOF) analysis helps to identify, possibly for the first time, the physical parameters responsible for the dominant modal fluctuations in the Yucatan Channel and the likely reason for the model eddy shedding periods. The EOF mode 1 and mode 2 represent the variations in cross-channel oscillations and in inflow transport into the Gulf, respectively. The third and fourth EOF modes together, represent variations in the deep current over the sill, with long periods similar to those observed by Maul et al. (1985). The dominant EOF modal periods, around 6, 8 and 11 months are almost identical to the most dominant observed periods of Loop Current eddy shedding found by Sturges and Leben (2000). A follow up study by Oey et al. (2003) provides further analysis of the effect of wind variations and Caribbean eddies on the eddy shedding frequency and mechanism.


This paper was written while Ms. Romanou was a post-doc with Chassignet. It reports the results of the MICOM studies over the full Gulf. The characteristics of rings (size, lifetimes, etc.) are compared with observations. There is also a discussion of comparisons of flow in Yucatan Channel with the observations of the Ensenada group. Ms. Romanou then went to a post-doctoral position at N.Y.U.

This paper was the result of several MMS projects, including the Gulf of Mexico deep flows collaborative study by Ezer-Sturges, the Gulf of Mexico deep flows and energetics study by Oey and collaborators, and the GOM hindcast system development efforts by Oey-Ezer. In this paper, the data assimilation methodology, previously developed for the Gulf Stream region (Ezer and Mellor, 1994, 1997), has been evaluated for the Gulf. The model’s hindcasts are compared with analysis of moored current meter data in DeSoto Canyon and with analysis of altimeter data, using the Singular Value Decomposition (SVD) method. The model results were found to compare well with the mean and variance of the currents in the Canyon, which seem to be largely influenced by the local topography. However, model results are only partly in agreement with the basic modes which describe the interaction between eddies and the Canyon circulation.
VII. REFERENCES


